Graph-based learning

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Outline



- Motivation
- 2 Graph Clustering
- Semi-Supervised Learning
- 4 Conclusion

Motivation

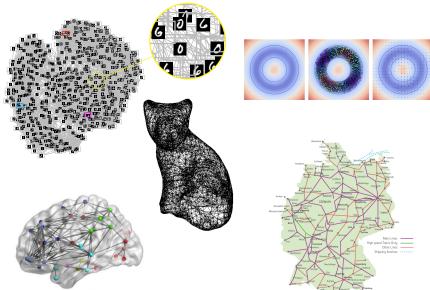
@ Graph Clustering

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Graph-Structured Data is Omnipresent



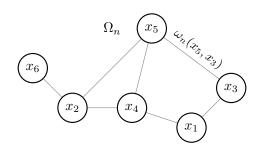


Weighted Graphs



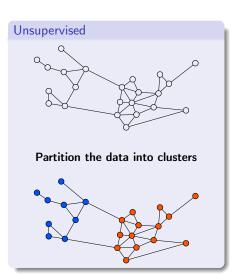
Definition

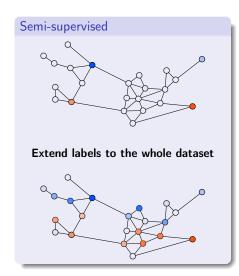
A finite weighted graph is a tuple $G=(\Omega,\omega)$, where Ω is a finite vertex set and $\omega:\Omega\times\Omega\to[0,\infty)$ is a (symmetric) weight function. We define $E:=\{(x,y)\subset\Omega:\omega_{xy}>0\}$ to be the set of edges of the graph.



Graph-Based Learning







What are the challenges with graph-based learning?

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- Convex relaxations
- Labeling guarantees
- Robustness and regularity
- Large data / continuum limits

Motivation

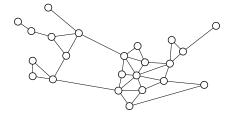
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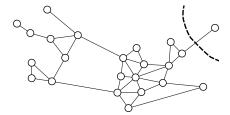


Idea: Subdivide the graph into two groups by means of a graph cut.



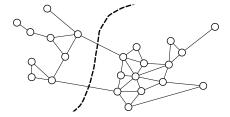


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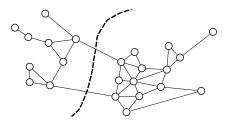


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Aim: Minimize the normalized cut energy

$$NCut(A) := \frac{Per(A)}{vol(A)} + \frac{Per(A^c)}{vol(A^c)},$$

where $\operatorname{Per}(A) := \sum_{x \in A, y \in A^c} \omega_{xy}$ is the perimeter of A, $\deg(x) := \sum_{y \in \Omega} \omega_{xy}$ is the degree of $x \in \Omega$, and $\operatorname{vol}(A) := \sum_{x \in A} \deg(x)$ is the volume of A.

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Convex Relaxation



The cut minimization problem $\min_{A \subset \Omega} \operatorname{NCut}(A)$ is a combinatoric optimization problem and NP-hard (Von Luxburg, 2007).

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Convex relaxation

$$\min_{u:\Omega \to \mathbb{R}} \left\{ \sum_{x,y \in \Omega} \omega_{xy} \left| \frac{u(x)}{\sqrt{\deg(x)}} - \frac{u(y)}{\sqrt{\deg(y)}} \right|^2 : \left\langle u, \sqrt{\deg} \right\rangle = 0, \|u\|^2 = 1 \right\},$$

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is equivalent to eigenvalue problem $-Lu=\lambda u$ for the normalized graph Laplacian

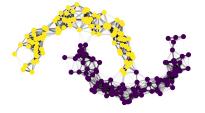
$$Lu(x) := \frac{1}{\sqrt{\deg(x)}} \sum_{y \in \Omega} \omega_{xy} \left(\frac{u(y)}{\sqrt{\deg(y)}} - \frac{u(x)}{\sqrt{\deg(x)}} \right).$$

Cheeger Inequality



Spectral clustering: Threshold the second eigenvector of the graph Laplacian.

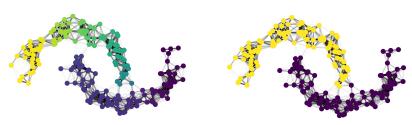




Cheeger Inequality



Spectral clustering: Threshold the second eigenvector of the graph Laplacian.



Theorem (Cheeger inequality, Chung, 2007)

Let $G=(\Omega,\omega)$ be such that $\deg(x)>0$ for all $x\in\Omega$, and let $\lambda_2\geq 0$ denote the second eigenvalue of -L. Then it holds

$$\frac{\lambda_2}{2} \le \min_{A \subset \Omega} \text{NCut}(A) \le \sqrt{8\lambda_2}.$$

Continuum Limits of Graph-Based Learning





Graph-Based Learning

- Given: Weighted graph $G_n = (\Omega_n, \omega_n)$ with $\#\Omega_n = n \in \mathbb{N}$.
- ullet Goal: $\mathbf{u}_n:\Omega_n o\mathbb{R}$ solving a clustering or labeling task
- Tool: graph PDE

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What happens with more and more data, $\#\Omega_n \to \infty$?

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 ${\sf graph} \ {\sf PDE} \to {\sf continuum} \ {\sf PDE}, \quad {\sf as} \ n \to \infty.$



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Spectral clustering for random geometric graphs $\{x_1,\ldots,x_n\}\stackrel{i.i.d.}{\sim} \rho \in \mathcal{P}(\mathcal{M})$ can be analyzed using graph Dirichlet-energies:

$$E_n(u) := \frac{1}{n^2 \varepsilon^2} \sum_{i,j=1}^n \eta \left(\frac{|x_i - x_j|}{\varepsilon_n} \right) \left| \frac{u(x_i)}{\sqrt{\deg_n(x_i)}} - \frac{u(x_j)}{\sqrt{\deg_n(x_j)}} \right|^2$$



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Theorem (LB and Slepčev, 2025)

If $\left(\frac{\log n}{n}\right)^{1/d^{(2)}} \ll \varepsilon_n \ll 1$, almost surely the Γ -limit of the functionals E_n is given by

$$\mathcal{E}(u) := \sum_{i=1}^{2} \frac{\sigma_{\eta}^{(i)}}{\beta_{\eta}^{(i)}} \int_{\mathcal{M}^{(i)}} \left| \nabla \left(\frac{u}{\sqrt{\rho|_{\mathcal{M}^{(i)}}}} \right) \rho|_{\mathcal{M}^{(i)}} \right|^{2} \mathrm{d} \operatorname{Vol}^{(i)} \ \, \text{if } u \in H^{1}_{\sqrt{\rho}}(\mathcal{M}) \ \, \text{and} \, \infty \, \, \text{else,}$$

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where $H^1_{\sqrt{\rho}}(\mathcal{M})$ is a tensorized Sobolev space with a trace condition on the intersection if $d^{(1)} = d^{(2)} = \dim(\mathcal{M}^{(1)} \cap \mathcal{M}^{(2)}) + 1$.

Motivation

Graph Clustering

Semi-Supervised Learning

4 Conclusion





Given:

- a data set $\Omega_n \subset \mathbb{R}^d$,
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a "smooth" function $\mathbf{u}_n:\Omega_n\to\mathbb{R}$ such that $\mathbf{u}=g$ on \mathcal{O}_n .





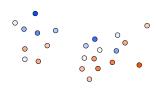
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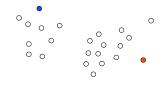
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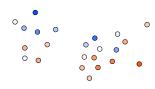
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Compute \mathbf{u}_n via graph PDE.

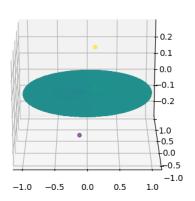


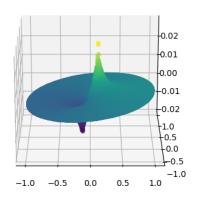
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Laplace Learning

Poisson Learning

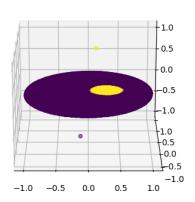


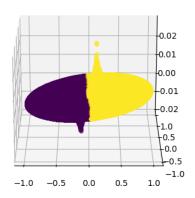


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Poisson Learning



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Find $\mathbf{u}_n:\Omega_n o \mathbb{R}$ such that

$$-L_n \mathbf{u}_n = \sum_{x \in \mathcal{O}_n} (g(x) - \overline{g}) \delta_x,$$

subject to $\sum_{x \in \Omega_n} \deg_n(x) u(x) = 0$.

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Continuum Problem

Find $u \in W^{1,1}(\Omega)$, distributional solution of

$$-\operatorname{div}(\rho^2 \nabla u) = \sum_{x \in \mathcal{O}} (g(x) - \overline{g}) \delta_x,$$

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- $g:\mathbb{R}^d o \{-1,1\}$ are binary labels, $\overline{g}:=\frac{1}{|\mathcal{O}|}\sum_{x\in\mathcal{O}}g(x)$ is the label mean,
- $\Omega_n := \{x_i\}_{i=1}^n$ with i.i.d. samples x_i with $\text{Law}(x_i) = \rho$,
- \mathcal{O} is a finite set and $\mathcal{O}_n = \{\pi_n(x) : x \in \mathcal{O}\}$ where $\pi_n : \Omega \to \Omega_n$ is a closest point projection,
- Label decision: $label(x) = sign(\mathbf{u}_n(x))$.



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Aims: convergence rates

Formal Main Result



Theorem (Formal, LB, Calder, et al., 2024)

If ρ and $\partial\Omega$ are $C^{1,1}$ and for

$$\left(\frac{\log n}{n}\right)^{\frac{1}{3d}} \ll \varepsilon_n \ll 1$$

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If $\rho \equiv const$ this can be improved to

$$\|\mathbf{u}_n - u\|_{\ell^1(\Omega_n)} \lesssim \varepsilon_n^{\frac{2-\sigma}{d+4}}$$

for any $\sigma > 0$.







Continuum mollification

Replace continuum data $\sum_{x \in \mathcal{O}} (g(x) - \overline{g}) \delta_x$ by $\sum_{x \in \mathcal{O}} (g(x) - \overline{g}) \varphi_x$ with $\operatorname{supp} \varphi_x \subset B(x,R)$ obtain quantitative L^1 -estimates in R.



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Discrete mollification

Mollify discrete data $\sum_{x\in\mathcal{O}}(g(x)-\overline{g})\delta_x$ with k steps of the graph heat equation and obtain quantitative estimates in k and ε .



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NB: Keeping track of all constants (which blow up) and optimizing over all parameters we obtain the final rate.

Motivation

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Conclusion



Challenges in graph-based learning:

- Realistic manifold assumptions
- Convergence rates
- Theoretical guarantees for sparse graphs

Applications:

- Data Science
- Grid-free solution of high-dimensional PDEs
- Digital twins?

References



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Continuum Mollification

We regularize the continuum equation by approximating the Dirac deltas:

$$-\operatorname{div}(\rho^2\nabla u)=\sum_{x\in\varGamma}a_x\delta_x\qquad\text{ and }\qquad-\operatorname{div}(\rho^2\nabla u_R)=\sum_{x\in\varGamma}a_x\varphi_x,$$

where supp $\varphi_x \subset B(x,R)$, $\varphi_x \geq 0$, and $\int_{B(x,R)} \varphi_x(y) dy = 1$.

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If in addition $\rho \equiv const$ and $\varphi_{x}(y) = R^{-d}\psi\left(\left|y-x\right|/R\right)$, then

$$||u-u_R||_{L^1(\Omega)} \lesssim \sum_{x\in \Gamma} |a_x| R^2.$$

Discrete Mollification

We define the random walk graph Laplacian:

$$\widehat{L}_n \mathbf{u}_n(x) := \frac{1}{\varepsilon_n^2 \deg_n(x)} L_n \mathbf{u}_n(x) = \frac{1}{\varepsilon_n^2} \left(\frac{1}{\deg_n(x)} \sum_{y \in \Omega_n} \omega_n(x, y) \mathbf{u}_n(y) - \mathbf{u}_n(x) \right).$$

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The graph heat kernel \mathcal{H}_k^x is the solution of the heat equation, starting with δ_x :

$$\mathcal{H}_{k+1}^x = \mathcal{H}_k^x - \varepsilon_n^2 \widehat{L}_n^T \mathcal{H}_k^x, \qquad \mathcal{H}_0^x = n\delta_x.$$

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Theorem (LB, Calder, et al., 2024)

It holds
$$\mathcal{H}_k * (\widehat{L}_n \mathbf{u}_n) = \widehat{L}_n (\mathcal{H}_k * \mathbf{u}_n).$$

Estimates on Mollified Problem

Let \mathbf{u}_n and $\mathbf{u}_n^{(k)} := \mathcal{H}_k^\cdot * \mathbf{u}_n$ solve

$$-\widehat{L}_n\mathbf{u}_n = \sum_{x \in \mathcal{O}} a_x \delta_x \qquad \text{ and } \qquad -\widehat{L}_n\mathbf{u}_n^{(k)} = \sum_{x \in \mathcal{O}} a_x \mathcal{H}_k^x.$$

Then it holds

$$\mathbf{u}_n - \mathbf{u}_n^{(k)} = \frac{n\varepsilon_n^2}{\deg_n} \sum_{x \in \mathcal{O}} a_x \sum_{j=0}^{k-1} \mathcal{H}_j^x.$$

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Using that $\deg_n \sim n$ and $\left\|\mathcal{H}^x_j\right\|_{\ell^1(\Omega_n)} = 1$ we get the estimate

$$\left\| \mathbf{u}_n - \mathbf{u}_n^{(k)} \right\|_{\ell^1(\Omega_n)} \lesssim k \varepsilon_n^2 \sum_{x \in \mathcal{O}} |a_x|$$

and will need to choose $1 \ll k \ll \frac{1}{\varepsilon_x^2}$.

Continuum Limit for Bounded Data

We consider Poisson equations with bounded right hand side:

$$-\operatorname{div}(\rho^2 \nabla u) = f \quad \text{and} \quad -L_n \mathbf{u}_n = f_n$$

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Theorem (LB, Calder, et al., 2024)

For all $R, \lambda_1, \lambda_2, \varepsilon_n, \delta > 0$ sufficiently small, and $q > \frac{d}{2}$ we have with high probability:

$$\begin{split} \|u - \mathbf{u}_n\|_{H^1(\mathcal{X}_n)}^2 &\lesssim \left(\|f_n - f\|_{\ell^1(\Omega_n)} + \|\operatorname{osc}_{\Omega \cap B(\cdot, \delta)} f\|_{L^1(\Omega)} \right) \left(\|f\|_{L^q(\Omega)} + \|f_n\|_{\ell^q(\Omega_n)} \right) \\ &+ \|f\|_{L^{\infty}(\Omega)}^2 \lambda_1 + \|f\|_{L^{\infty}(\partial_{4\varepsilon_n}\Omega)}^2 \varepsilon_n + \|f_n\|_{\ell^2(\Omega_n)} \|f_n\|_{\ell^2(\Omega_n \cap \partial_{2R}\Omega)} \\ &+ \left(\|f_n\|_{\ell^2(\Omega_n)}^2 + \|f\|_{L^2(\Omega)}^2 \right) \left(\frac{\delta}{\varepsilon_n} + \varepsilon_n + \lambda_1^2 + \lambda_2 \right). \end{split}$$

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We choose $f_n = \sum_{x \in \mathcal{O}} a_x \mathcal{H}^x_k$ and prove discrete-to-continuum convergence rates towards a k-fold convolution $f := \sum_{x \in \mathcal{O}} a_x \rho(x)^{-1} \mathcal{M}^k_{\varepsilon}(\delta_x)$.