# The role of Artificial Intelligence in the future of mathematics 

Amaury Hayat<br>CERMICS - Ecole des Ponts Paristech

FAU MoD Lecture

Thursday January 11th, 2024

École des Ponts
ParisTech

## Introduction

Social networks
(5) 0

Emails and apps

Platforms


## Introduction



## Introduction

Over the past year, we have heard a lot about the progress of AI, particularly in one field: AI for language.

## ChatGPT

## LLaMA |' mistral by 0 Meta ${ }^{\text {i }}$ AI_

## Introduction

## How did we get there?

## Introduction

## How did we get there?

- Al for language is not new: research started $\sim 1950$


## Introduction

## How did we get there?

- Al for language is not new: research started $\sim 1950$
- A turning point in the years 2010s with the neural networks (large progress in translation, etc.)


## Introduction

## How did we get there?

- Al for language is not new: research started $\sim 1950$
- A turning point in the years 2010s with the neural networks (large progress in translation, etc.)
- Another turning point in 2017: the Transformer.


## A turning point in 2017: the Transformer

```
Attention is all you need
A Vaswani, N Shazeer, N Parmar... - Advances in neural ..., 2017 - proceedings.neurips.cc
... to attend to all positions in the decoder up to and including that position. We need to prevent
... We implement this inside of scaled dot-product attention by masking out (setting to -\infty) ...
$ Enregistrer \0 Citer Cité 91677 fois Autres articles Les 62 versions $)
```

- An attention mechanism, which allows it to focus on the right pieces of a sentence

Hope is a good thing, maybe the best of things and no good thing ever dies.


## Introduction

2018 - GPT - an autoregressive transformer.


A: Hope is a good thing, maybe the best of things and no good thing ever dies.

## Outline of the Lecture



1. Al today in mathematics

2. Can Al prove theorems?

## Outline of the Lecture



1. Al today in mathematics

2. Can Al prove theorems?

## Solving maths problems with a computer

## Solving maths problems with a computer

## Conjecture (Euler, 1769)

If there exist integers $a_{1}, a_{2}, \ldots, a_{k}, b$, and $n$ such that

$$
a_{1}^{n}+a_{2}^{n}+\ldots+a_{k}^{n}=b^{n},
$$

then $k \geq n$.


A problem open for almost 200 years

## Solving maths problems with a computer

Lander and Parkin (1966)

## Solving maths problems with a computer

Lander and Parkin (1966)

$$
27^{5}+84^{5}+110^{5}+133^{5}=144^{5}
$$

## Solving maths problems with a computer

## COUNTEREXAMPLE TO EULER'S CON JECTURE ON SUMS OF LIKE POWERS

BY L. J. LANDER AND T. R. PARKIN

Communicated by J. D. Swift, June 27, 1966
A direct search on the CDC 6600 yielded

$$
27^{5}+84^{5}+110^{5}+133^{5}=144^{5}
$$

as the smallest instance in which four fifth powers sum to a fifth power. This is a counterexample to a conjecture by Euler [1] that at least $n n$th powers are required to sum to an $n$th power, $n>2$.

Reference

1. L. E. Dickson, History of the theory of numbers, Vol. 2, Chelsea, New York, 1952, p. 648.

## Solving maths problems with a computer

Proof of Keller's Conjecture (Brakensiek, Heule, Mackey, Narváez, 2019)

- A proof with many "simple cases" to check
- Many = far too many for a human



## Solving maths problems with a computer

Proof of Keller's Conjecture (Brakensiek, Heule, Mackey, Narváez, 2019)

- A proof with many "simple cases" to check
- Many = far too many for a human
- Size of the proof:



## Solving maths problems with a computer

Proof of Keller's Conjecture (Brakensiek, Heule, Mackey, Narváez, 2019)

- A proof with many "simple cases" to check
- Many = far too many for a human

■ Size of the proof: 200Gb $\sim 10$ Wikipedias


Conclusion: Computers have been used to prove theorems for a long time.

Conclusion: Computers have been used to prove theorems for a long time.

## Can Al solve more complicated problems?

## Problems where the difficulty is not just combinatorial?

## Al in Mathematics Today

Three examples

■ Stability of dynamical systems

- Control theory
- Topology


## Al in Mathematics Today

Three examples

■ Stability of dynamical systems

- Control theory
- Topology


## Stability of Dynamical Systems

A system of differential equations

$$
\dot{x}(t)=f(x(t)),
$$

## Stability of Dynamical Systems

A point in free fall.

$$
\begin{aligned}
\dot{y}(t) & =v(t) \\
\dot{v}(t) & =-g,
\end{aligned}
$$



## Stability of Dynamical Systems

The evolution of a chemical reaction

$$
\begin{aligned}
& \dot{x}=-\alpha x(t)+(1-x(t)), \\
& \dot{y}=\alpha x(t)-y(t),
\end{aligned}
$$



## Stability of Dynamical Systems

The Solow model in economics

$$
\begin{aligned}
\dot{K}(t) & =s F(K(t), a L(t))-\delta K v(t) \\
\dot{L}(t) & =n L(t),
\end{aligned}
$$



A system of differential equations

$$
\dot{x}(t)=f(x(t))
$$

A system of differential equations

$$
\dot{x}(t)=f(x(t))
$$

where $x(t) \in \mathbb{R}^{n}, f \in C^{1}\left(\mathbb{R}^{n}\right)$ and $f(0)=0$.

A system of differential equations

$$
\dot{x}(t)=f(x(t))
$$

where $x(t) \in \mathbb{R}^{n}, f \in C^{1}\left(\mathbb{R}^{n}\right)$ and $f(0)=0$.

## Question (System Stability)

Is it true that for every $\varepsilon>0$, there exists $\delta>0$ such that if the initial condition satisfies $\|x(0)\| \leq \delta$ then the solution $x(t)$ exists for all $t \in[0,+\infty)$ and

$$
\|x(t)\| \leq \varepsilon, \forall t \in[0,+\infty)
$$

A system of differential equations

$$
\begin{gathered}
\dot{x}(t)=f(x(t)) \\
\text { where } x(t) \in \mathbb{R}^{n}, f \in C^{1}\left(\mathbb{R}^{n}\right) \text { and } f(0)=0 .
\end{gathered}
$$

## Question (System Stability)

Is it true that for every $\varepsilon>0$, there exists $\delta>0$ such that if the initial condition satisfies $\|x(0)\| \leq \delta$ then the solution $x(t)$ exists for all $t \in[0,+\infty)$ and

$$
\|x(t)\| \leq \varepsilon, \forall t \in[0,+\infty)
$$

- Are all solutions bounded if the initial condition is sufficiently small?

A system of differential equations

$$
\dot{x}(t)=f(x(t))
$$

where $x(t) \in \mathbb{R}^{n}, f \in C^{1}\left(\mathbb{R}^{n}\right)$ and $f(0)=0$.

## Question (System Stability)

Is it true that for every $\varepsilon>0$, there exists $\delta>0$ such that if the initial condition satisfies $\|x(0)\| \leq \delta$ then the solution $x(t)$ exists for all $t \in[0,+\infty)$ and

$$
\|x(t)\| \leq \varepsilon, \forall t \in[0,+\infty)
$$

- Are all solutions bounded if the initial condition is sufficiently small?



## Stability of Dynamical Systems

A problem that has interested mathematicians for over a hundred years.


## Stability of Dynamical Systems

A significant advancement: Lyapunov functions

## Theorem

If there exists a function $V \in C^{1}\left(\mathbb{R}^{n} ; \mathbb{R}\right)$ such that for all $x \in \mathbb{R}^{n}$

$$
V(x)>V(0), \quad \text { and } \quad \nabla V(x) \cdot f(x) \leq 0,
$$

and

$$
\lim _{\|x\| \rightarrow+\infty} V(x)=+\infty,
$$

then the system is stable.

A. Lyapunov (1857-1918)

## Stability of Dynamical Systems

A significant advancement: Lyapunov functions

## Theorem

If there exists a function $V \in C^{1}\left(\mathbb{R}^{n} ; \mathbb{R}\right)$ such that for all $x \in \mathbb{R}^{n}$

$$
V(x)>V(0), \quad \text { and } \quad \nabla V(x) \cdot f(x) \leq 0
$$

and

$$
\lim _{\|x\| \rightarrow+\infty} V(x)=+\infty,
$$

then the system is stable.

A. Lyapunov (1857-1918)

Nothing tells us how to find such a function $V$...

## Stability of Dynamical Systems

Nothing tells us how to find such a function $V$...

And it's not a simple problem.

## Stability of Dynamical Systems

Nothing tells us how to find such a function $V$...
And it's not a simple problem.

$$
\dot{x}(t)=\left(\begin{array}{c}
-6 x_{1}^{4}(t) x_{2}^{5}(t)-3 x_{1}^{7}(t) x_{3}^{2}(t) \\
3 x_{1}^{9}(t)-6 x_{1}^{2}(t) x_{2}^{5}(t) x_{3}^{2}(t) \\
-4 x_{1}^{2}(t) x_{3}^{5}(t)
\end{array}\right)
$$

## Stability of Dynamical Systems

Nothing tells us how to find such a function $V$...
And it's not a simple problem.

$$
\dot{x}(t)=\left(\begin{array}{c}
-6 x_{1}^{4}(t) x_{2}^{5}(t)-3 x_{1}^{7}(t) x_{3}^{2}(t) \\
3 x_{1}^{9}(t)-6 x_{1}^{2}(t) x_{2}^{5}(t) x_{3}^{2}(t) \\
-4 x_{1}^{2}(t) x_{3}^{5}(t)
\end{array}\right)
$$

The system is stable, a Lyapunov function is

$$
V(x)=x_{1}^{6}+2\left(x_{2}^{6}+x_{3}^{4}\right)
$$

## Stability of Dynamical Systems

A globally asymptotically stable polynomial vector field with no polynomial Lyapunov function
Publisher: IEEE

```
Cite This
```

© PDF
Amir Ali Ahmadi ; Miroslav Krstic ; Pablo A. Parrilo All Authors

| 39 | 399 |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Cites in | Full | ( ${ }^{\text {a }}$ | (C) | - |

Papers Text Views

## Stability of Dynamical Systems

Today, more than a hundred years later, it is still an open question:
there is still no systematic way to construct a Lyapunov function.

## Stability of Dynamical Systems

Today, more than a hundred years later, it is still an open question:
there is still no systematic way to construct a Lyapunov function.
$\rightarrow$ We resort to intuition

## Stability of Dynamical Systems

- Intuition, an important concept in mathematics.


## Stability of Dynamical Systems

- Intuition, an important concept in mathematics.
- In a number of cases, intuition resembles a kind of pattern recognition. You've seen plenty of examples, and this gives you an idea of how to proceed in a case you've never seen.


## Stability of Dynamical Systems

- Intuition, an important concept in mathematics.
- In a number of cases, intuition resembles a kind of pattern recognition. You've seen plenty of examples, and this gives you an idea of how to proceed in a case you've never seen.
- Can we train an Al to have better intuition than us?


## Stability of Dynamical Systems

■ Intuition, an important concept in mathematics.

- In a number of cases, intuition resembles a kind of pattern recognition. You've seen plenty of examples, and this gives you an idea of how to proceed in a case you've never seen.
- Can we train an Al to have better intuition than us?

First task for AI: guessing Lyapunov functions

## Stability of Dynamical Systems

■ Intuition, an important concept in mathematics.

- In a number of cases, intuition resembles a kind of pattern recognition. You've seen plenty of examples, and this gives you an idea of how to proceed in a case you've never seen.
- Can we train an AI to have better intuition than us?

First task for Al: guessing Lyapunov functions

$$
\dot{x}(t)=\left(\begin{array}{c}
-6 x_{1}^{4}(t) x_{2}^{5}(t)-3 x_{1}^{7}(t) x_{3}^{2}(t) \\
3 x_{1}^{9}(t)-6 x_{1}^{2}(t) x_{2}^{5}(t) x_{3}^{2}(t) \\
-4 x_{1}^{2}(t) x_{3}^{5}(t)
\end{array}\right) \quad \rightarrow \quad \text { Yes, } V(x)=x_{1}^{6}+2\left(x_{2}^{6}+x_{3}^{4}\right)
$$

## Stability of Dynamical Systems

Train an AI to have an intution of Lyapunov function (Alfarano, Charton, A.H., 2023).

Neural network architecture: Transformer ( $\sim 1000$ smaller than ChatGPT)

Procedure:

1. Generate a set of systems and associated Lyapunov functions.
2. Encode the examples
3. Train the Transformer (supervised learning)

## Stability of Dynamical Systems

Procedure:

1. Generate a set of systems and associated Lyapunov functions.
2. Encode the examples

3. Train the Transformer (supervised learning)

## Stability of Dynamical Systems

## Results

| Type | n equations | degree | SOSTOOLS $^{1}$ | Al |
| :---: | :---: | :---: | :---: | :---: |
| polynomial | $2-3$ | 8 | $78 \%$ | $\mathbf{9 9 . 3 \%}$ |
| polynomial | $3-6$ | 12 | $16 \%$ | $\mathbf{9 5 . 1 \%}$ |
| polynomial (fwd) | $2-3$ | 6 | N/A | $\mathbf{8 3 . 1 \%}$ |
| Non-polynomial | N/A | N/A | N/A | $\mathbf{9 7 . 8 \%}$ |

[^0]
## Stability of Dynamical Systems

## Results

| Type | n equations | degree | SOSTOOLS $^{1}$ | Al |
| :---: | :---: | :---: | :---: | :---: |
| polynomial | $2-3$ | 8 | $78 \%$ | $\mathbf{9 9 . 3 \%}$ |
| polynomial | $3-6$ | 12 | $16 \%$ | $\mathbf{9 5 . 1 \%}$ |
| polynomial (fwd) | $2-3$ | 6 | N/A | $\mathbf{8 3 . 1 \%}$ |
| Non-polynomial | N/A | N/A | N/A | $\mathbf{9 7 . 8 \%}$ |

Mathematicians accuracy: $\sim 25 \%$

[^1]
## Al in Mathematics Today

Three examples

- Stability of dynamical systems

■ Control theory

- Topology


## Control of a Differential System

Evolution of the mosquito population

$$
\left\{\begin{aligned}
\dot{E} & =\beta_{E} F\left(1-\frac{E}{K}\right)-\left(\nu_{E}+\delta_{E}\right) E \\
\dot{M} & =(1-\nu) \nu_{E} E-\delta_{M} M \\
\dot{F} & =\nu \nu_{E} E \frac{M}{M+M_{s}}-\delta_{F} F \\
\dot{M}_{s} & =u-\delta_{s} M_{s}
\end{aligned}\right.
$$

$E(t)$ represents mosquito eggs, $F(t)$ fertilized females, $M(t)$ males, $M_{s}(t)$ sterile males. $u$ is the flow of sterile mosquitoes that we release. This is what is called control.

## Control of a Differential System

Evolution of the mosquito population

$$
\left\{\begin{aligned}
\dot{E} & =\beta_{E} F\left(1-\frac{E}{K}\right)-\left(\nu_{E}+\delta_{E}\right) E \\
\dot{M} & =(1-\nu) \nu_{E} E-\delta_{M} M \\
\dot{F} & =\nu_{E} E \frac{M}{M+M_{s}}-\delta_{F} F \\
\dot{M}_{s} & =u-\delta_{s} M_{s}
\end{aligned}\right.
$$

$E(t)$ represents mosquito eggs, $F(t)$ fertilized females, $M(t)$ males, $M_{s}(t)$ sterile males. $u$ is the flow of sterile mosquitoes that we release. This is what is called control.

$$
u=f\left(M+M_{s}, F+F_{s}\right)
$$

with $F_{s}=F M / M_{s}$.

## Control of a Differential System

$E(t)$ represents mosquito eggs, $F(t)$ fertilized females, $M(t)$ males, $M_{s}(t)$ sterile males. $u$ is the flow of sterile mosquitoes that we release. This is what is called control.

$$
u=f\left(M+M_{s}, F+F_{s}\right)
$$

## Question

Is it possible to find $f$ such that the system is stable and

$$
\lim _{t \rightarrow+\infty}\|E(t), M(t), F(t)\|=0 \text { and } \lim _{t \rightarrow+\infty}\left\|M_{s}(t)\right\|=\varepsilon
$$

with $\varepsilon$ as small as desired?

## Control of a Differential System

$E(t)$ represents mosquito eggs, $F(t)$ fertilized females, $M(t)$ males, $M_{s}(t)$ sterile males. $u$ is the flow of sterile mosquitoes that we release. This is what is called control.

$$
u=f\left(M+M_{s}, F+F_{s}\right)
$$

## Question

Is it possible to find $f$ such that the system is stable and

$$
\lim _{t \rightarrow+\infty}\|E(t), M(t), F(t)\|=0 \text { and } \lim _{t \rightarrow+\infty}\left\|M_{s}(t)\right\|=\varepsilon
$$

with $\varepsilon$ as small as desired?
An open question

## Control of a Differential System

Principle of the approach (Agbo Bidi, Coron, A.H., Lichtlé, 2023)


## Control of a Differential System

Principle of the approach (Agbo Bidi, Coron, A.H., Lichtlé, 2023)


1 Transform the equations using a well-chosen numerical scheme.
2 Train a Reinforcement Learning (RL) model. The AI trains by trial and error and tries to maximize a well-chosen objective.
3 Deduce the mathematical control, from the numerical control.
4 Verify that it is a solution to the problem.

## Control of a Differential System



$$
u=f\left(M+M_{s}, F+F_{s}\right)
$$

## Control of a Differential System




$$
u=f\left(M+M_{s}, F+F_{s}\right)
$$

## Control of a Differential System

$$
u_{\mathrm{reg}}\left(M+M_{s}, F+F_{s}\right)= \begin{cases}u_{\mathrm{reg}}^{\mathrm{left}}\left(M+M_{s}, F+F_{s}\right) & \text { if } M+M_{s}<M^{*}, \\ u_{\mathrm{rghg}}^{\mathrm{irght}}\left(M+M_{s}, F+F_{s}\right) & \text { otherwise }\end{cases}
$$

## Control of a Differential System

$$
\begin{aligned}
& u_{\text {reg }}\left(M+M_{s}, F+F_{s}\right)= \begin{cases}u_{\mathrm{reg}}^{\mathrm{left}}\left(M+M_{s}, F+F_{s}\right) & \text { if } M+M_{s}<M^{*}, \\
u_{\mathrm{regh}}^{\text {right }}\left(M+M_{s}, F+F_{s}\right) & \text { otherwise, }\end{cases} \\
& u_{\text {reg }}^{\text {left }}=\left\{\begin{array}{ll}
\varepsilon & \text { if } I_{1}\left(F+F_{s}\right)>\alpha_{2}, \\
u_{\max }\left(\alpha_{2}-I_{1}\right) & \text { if } I_{1} \in\left(\alpha_{1}, \alpha_{2}\right], \\
u_{\max } & \text { otherwise, and }
\end{array} \quad u_{\text {reg }}^{\text {right }}= \begin{cases}\varepsilon & \text { if } I_{2}>\alpha_{2}, \\
u_{\text {max }}\left(\alpha_{2}-I_{2}\right) & \text { if } I_{2} \in\left(\alpha_{1}, \alpha_{2}\right], \\
u_{\text {max }} & \text { otherwise. }\end{cases} \right.
\end{aligned}
$$

where $I_{1}(x)=\frac{\log M^{*}}{\log \left(F+F_{s}\right)}$ and $I_{2}(x, y)=\frac{\log \left(M+M_{s}\right)}{\log \left(F+F_{s}\right)}$,

## Control of a Differential System

Final control

$$
u(t)= \begin{cases}\varepsilon & \text { if } \frac{\log \left(M+M_{s}\right)}{\log \left(F+F_{s}\right)}>\alpha_{2} \\ u_{\max } & \text { otherwise }\end{cases}
$$

## Control of a Differential System

Final control

$$
u(t)= \begin{cases}\varepsilon & \text { if } \frac{\log \left(M+M_{s}\right)}{\log \left(F+F_{s}\right)}>\alpha_{2} \\ u_{\max } & \text { otherwise }\end{cases}
$$



$$
\varepsilon>0
$$

## Control of a Differential System

Final control

$$
u= \begin{cases}\varepsilon & \text { if } \frac{\log \left(M+M_{s}\right)}{\log \left(F+F_{s}\right)}>\alpha_{2} \\ u_{\max } & \text { otherwise }\end{cases}
$$



$$
\varepsilon=0
$$

## Control of a Differential System

Final control

$$
u= \begin{cases}\varepsilon & \text { if } \frac{\log \left(M+M_{s}\right)}{\log \left(F+F_{s}\right)}>\alpha_{2} \\ u_{\max } & \text { otherwise }\end{cases}
$$



$$
\varepsilon=0
$$

We can see a mathematical bifurcation with our "Al-augmented intuition".

## Al Today in Mathematics

Three examples

■ Stability of dynamical systems

- Control theory
- Topology


## Topology

Advancing mathematics by guiding human intuition with AI, 2021, Davies et al.
Principle:
■ We have mathematical objects $z$ with quantities $X(z)$ and $Y(z)$. We would like to know if there is a link between the two.

## Topology

Advancing mathematics by guiding human intuition with AI, 2021, Davies et al.
Principle:
■ We have mathematical objects $z$ with quantities $X(z)$ and $Y(z)$. We would like to know if there is a link between the two.

■ We train a neural network to predict $Y(z)$ from $X(z)$
■ We try to understand the function learned by the neural network

$$
Y(z)=\hat{f}(X(z))
$$

## Topology

Advancing mathematics by guiding human intuition with Al, 2021, Davies et al.
Principle:
■ We have mathematical objects $z$ with quantities $X(z)$ and $Y(z)$. We would like to know if there is a link between the two.

- We train a neural network to predict $Y(z)$ from $X(z)$

■ We try to understand the function learned by the neural network

$$
Y(z)=\hat{f}(X(z))
$$

In particular, the link between hyperbolic and algebraic invariants of knots (embedding of a circle in $\mathbb{R}^{3}$ ).


## Al in Mathematics Today

- AI is already useful in the practice of mathematics and has solved several difficult problems.
- Al is trained to have better intuition than humans on a specific problem.
- This augmented intuition allows us to bypass the difficulty of the problem.


## Future of Mathematical AI

## Can an Al prove a mathematical result on its own?

## Can an AI reason?

## Outline of the Presentation



1. Al today in mathematics

2. Can Al prove theorems?

## Al for Mathematical Proof

■ Can an Al find a proof for a mathematical statement?

- Related question: can we automate human reasoning?


## Al for Mathematical Proof

- Can an AI find a proof for a mathematical statement? Many research groups around the world (Ecole des Ponts, Cambridge, Meta AI, OpenAI, etc.)
- Related question: can we automate human reasoning? A research group led by Timothy Gowers in Cambridge.


## Al for Mathematical Proof

First approach: training a Transformer (GPT-f, Polu, Sutskever, 2020)

$$
\begin{aligned}
& \text { Question } \\
& \text { Let } a>0 \text { and } b>0 \text {, such that } \\
& a b=b-a \text {, show that } \\
& \qquad \frac{a}{b}+\frac{b}{a}-a b=2
\end{aligned}
$$

## Al for Mathematical Proof

First approach: training a Transformer (GPT-f, Polu, Sutskever, 2020)

$$
\begin{aligned}
& \text { Question } \\
& \text { Let } a>0 \text { and } b>0 \text {, such that } \\
& a b=b-a \text {, show that } \\
& \qquad \frac{a}{b}+\frac{b}{a}-a b=2
\end{aligned}
$$

Ilya Sutskever: The OpenAI Genius Who Told Sam Altman He Was Fired
Company's chief scientist led a board coup against one of the most prominent figures in Silicon Valley
-4. sulver
Co-Founder and Chief Scientist of OpenAl
Adresse e-mail validée de openai.com - Page d'accueil
Machine Learning Neural Networks Artificial Intelligence Deep Learning


## Al for Mathematical Proof

First approach: training a Transformer (GPT-f, Polu, Sutskever, 2020)

$$
\begin{aligned}
& \text { Question } \\
& \text { Let } a>0 \text { and } b>0 \text {, such that } \\
& a b=b-a \text {, show that } \\
& \qquad \frac{a}{b}+\frac{b}{a}-a b=2
\end{aligned}
$$

## Al for Mathematical Proof

Input: Math statement


## Al for Mathematical Proof

Input: Math statement


## Al for Mathematical Proof

## Question

Let $a>0$ and $b>0$, such that $a b=b-a$, show that

$$
\frac{a}{b}+\frac{b}{a}-a b=2
$$

Procedure: train it with examples: (exercises, proofs)

- The hope is that by showing it enough examples, the AI will be capable of learning to reason, just by learning to predict the next step each time.


## Al for Mathematical Proof

## Question

Let $a>0$ and $b>0$, such that $a b=b-a$, show that

$$
\frac{a}{b}+\frac{b}{a}-a b=2
$$

Procedure: train it with examples: (exercises, proofs)

■ The hope is that by showing it enough examples, the AI will be capable of learning to reason, just by learning to predict the next step each time.

## Al for Mathematical Proof

## Question

Let $a>0$ and $b>0$, such that $a b=b-a$, show that

$$
\frac{a}{b}+\frac{b}{a}-a b=2
$$

Procedure: train it with examples: (exercises, proofs)

■ The hope is that by showing it enough examples, the AI will be capable of learning to reason, just by learning to predict the next step each time.

Enough $=$ sufficiently diverse and sufficiently numerous

## Al for Mathematical Proof

We have very few data available (especially formal).

## Al for Mathematical Proof

We have very few data available (especially formal).

## Question

Let $a>0$ and $b>0$, such that $a b=b-a$, show that

$$
\frac{a}{b}+\frac{b}{a}-a b=2
$$

informal language

```
theorem Exercice_1
(a b : \mathbb{R})
(ho: a > 0)
(h1: b > 0)
(h2: a*b = b-a) :
a/b+b/a-2*(a*b) = 2 :=
begin
sorry,
end
```

formal language

## Al for Mathematical Proof

We have very few data available (especially formal).

## Question

Let $a>0$ and $b>0$, such that $a b=b-a$, show that

$$
\frac{a}{b}+\frac{b}{a}-a b=2
$$

informal language

```
theorem Exercice_1
(a b : \mathbb{R}
(he: a > 0)
(h1: b > 0)
(h2: a*b = b-a) :
a/b+b/a-2*(a*b) = 2 :=
begin
sorry,
end
```

formal language
Lean: $\sim 100,000$ theorems. A large dataset for humans, a small dataset for AI.

## Al for Mathematical Proof

We have very few data available (especially formal).

## Question

Let $a>0$ and $b>0$, such that $a b=b-a$, show that

$$
\frac{a}{b}+\frac{b}{a}-a b=2
$$

informal language

```
theorem Exercice_1
(a b : \mathbb{R}
(he: a > 0)
(h1: b > 0)
(h2: a*b = b-a) :
a/b+b/a-2*(a*b) = 2 :=
begin
sorry,
end
```

formal language
Lean: $\sim 100,000$ theorems. A large dataset for humans, a small dataset for AI. $\rightarrow$ Limit of the approach

## AI for Mathematical Proof

We have very few data available (especially formal).

## Question

Let $a>0$ and $b>0$, such that $a b=b-a$, show that

$$
\frac{a}{b}+\frac{b}{a}-a b=2
$$

informal language

```
theorem Exercice_1
(a b : \mathbb{R}
(ho: a > 0)
(h1: b > 0)
(h2: a*b = b-a) :
a/b+b/a-2*(a*b) = 2 :=
begin
sorry,
end
```

formal language
Lean: $\sim 100,000$ theorems. A large dataset for humans, a small dataset for AI. $\rightarrow$ Limit of the approach

LeanLlama F. Glöckle et al. 2023 (Temperature-scaled large language models for Lean proofstep prediction)

## Al for Mathematical Proof

Second approach: treat mathematics as a game (Lample, Lachaux, Lavril, Martinet, Hayat, Ebner, Rodriguez, Lacroix, 2022)

## Al for Mathematical Proof

Second approach: treat mathematics as a game (Lample, Lachaux, Lavril, Martinet, Hayat, Ebner, Rodriguez, Lacroix, 2022)


Deepmind (2017)

## Al for Mathematical Proof

Second approach: treat mathematics as a game (Lample, Lachaux, Lavril, Martinet, Hayat, Ebner, Rodriguez, Lacroix, 2022)



You won!

Deepmind (2017)

## Al for Mathematical Proof

## Main difficulties:

- two-player game vs. solo against a goal.
- In chess, when you play a move you always have a single game. In mathematics: one statement $\rightarrow$ multiple statements
- Difficult in mathematics to know automatically in the middle of a proof what the probability of succeeding is.

- The number of possibilities is much, much larger in mathematics


## Al for Mathematical Proof

Main difficulties:

- two-player game vs. solo against a goal.
- In chess, when you play a move you always have a single game. In mathematics: one statement $\rightarrow$ multiple statements
- Difficult in mathematics to know automatically in the middle of a proof what the probability of succeeding is.

- The number of possibilities is much, much larger in mathematics


## Al for Mathematical Proof

In practice

- Two transformers: $P_{\theta}$ which predicts a tactic, $c_{\theta}$ which predicts the difficulty of proving a statement (goal, hypothesis, etc.).
- An intelligent proof search that sees the proof as a tree and combines $P_{\theta}$, $c_{\theta}$ and a tree expansion.

Selection


Expansion


Back-propagation


- Training of $P_{\theta}$ and $c_{\theta}$ as and when what has been successful


## Al for Mathematical Proof

## Results

Exercises at the undergraduate level...
... 30 to $60 \%$ of middle school / high school exercises up to Olympiad level...
...and a few exercises from the International Mathematical Olympiads

## Al for Mathematical Proof

Results

Exercises at the undergraduate level...
... 30 to $60 \%$ of middle school / high school exercises up to Olympiad level...
...and a few exercises from the International Mathematical Olympiads

## Exercise

Show that for all $n \in \mathbb{N}, 7$ does not divide $2^{n}+1$.

## Al for Mathematical Proof

Results

Exercises at the undergraduate level...
... 30 to $60 \%$ of middle school / high school exercises up to Olympiad level...
...and a few exercises from the International Mathematical Olympiads

## Exercise

Show that for all $n \in \mathbb{N}, 7$ does not divide $2^{n}+1$.
(Lample, Lachaux, Lavril, Martinet, Hayat, Ebner, Rodriguez, Lacroix, 2022)

## Al for Mathematical Proof

Results

Exercises at the undergraduate level...
... 30 to $60 \%$ of middle school / high school exercises up to Olympiad level...
...and a few exercises from the International Mathematical Olympiads

## Exercise

Show that for all $n \in \mathbb{N}, 7$ does not divide $2^{n}+1$.
(Lample, Lachaux, Lavril, Martinet, Hayat, Ebner, Rodriguez, Lacroix, 2022)

## Unexpected outcomes

## French Al start-up Mistral reaches unicorn status, marking its place as Europe's rival to OpenAI

Mistral's value has increased more than sevenfold in six months. It raised nearly €500 million in November and $€ 105$ million in its first funding round.
(Euronews 11/12/2023)

## Al for Mathematical Proof

Perspectives:
■ Add (approximations of) human reasoning.

- Add more organized reasoning with a hierarchy of tasks and a foresight of intermediate tasks.

■ Obtain more formal data through self-formalization (Wu et al., Jiang et al. 2022).

## Conclusion

- AI is already useful in the practice of mathematics
- AI for proving theorems is only beginning, and there are many ideas... and much to do.

■ The practice of mathematics will probably change... and that's okay.

- Al will not replace mathematicians but will instead enhance them.


## Conclusion

## Thank you for your attention


[^0]:    ${ }^{1}$ Existing method.

[^1]:    ${ }^{1}$ Existing method.

